## Galilean invariance of the work-energy theorem

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**Abstract:** The Galilean invariance of the work-energy theorem of Newtonian Mechanics is explicitly demonstrated.

*Definition:* A physical statement of Newtonian Mechanics is said to be *Galilean invariant* if it is valid with respect to all *inertial observers* (cf. Sec. 3.1 of [1]). If this statement is expressible by means of a mathematical equation, this equation must assume the *same form* in all *inertial frames of reference*.

Consider any two inertial observers O and O' with corresponding coordinate systems (or systems of axes) (x, y, z) and (x', y', z'). Let  $\vec{V}$  be the velocity of O' relative to O. Clearly, this velocity is constant in time.

Consider also a particle of mass *m*, moving with velocity  $\vec{v}$  and acceleration  $\vec{a}$  with respect to *O*, and with velocity  $\vec{v}'$  and acceleration  $\vec{a}'$  with respect to *O'*. As shown in Sec. 2.8 of [1],

$$\vec{v}' = \vec{v} - \vec{V} \tag{1}$$
$$\vec{a}' = \vec{a}$$

By Newton's  $2^{nd}$  law, the total force on *m* according to *O* and *O*' is

$$\vec{F} = d\vec{p} / dt = m\vec{a}$$
 and  $\vec{F}' = d\vec{p}' / dt = m\vec{a}'$ .

respectively, where  $\vec{p} = m\vec{v}$  and  $\vec{p}' = m\vec{v}'$ . In view of (1), then,

$$\vec{F} = \vec{F}' \tag{2}$$

Assume now that the particle *m* is inside a force field  $\vec{F}(\vec{r})$  and moves from point *A* to point *B* along some curve in space. The inertial observers *O* and *O'* will generally perceive *different* trajectories of *m* from *A* to *B*. Both observers, however, define force according to Newton's 2<sup>nd</sup> law. Given that the work-energy theorem is a direct consequence of that law (see Sec. 4.3 of [1]), this theorem must be valid for both observers. That is,  $W = \Delta E_k$  and, independently,  $W' = \Delta E_k'$ , where *W* is the work done on *m* by the field along the path *AB*, while  $\Delta E_k = E_{k,B} - E_{k,A}$  is the change in the particle's kinetic energy along that path.

Let us now verify explicitly that, if  $W = \Delta E_k$  for observer *O*, then  $W' = \Delta E_k'$  for any other inertial observer *O'*.

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At time t the particle m passes through the trajectory point with position vector  $\vec{r}(t)$  relative to observer O, or  $\vec{r}'(t)$  relative to observer O'. By (2), both observers record the same force on m at this instant, i.e.,

$$\vec{F}'(\vec{r}'(t)) = \vec{F}(\vec{r}(t)) \quad \text{or simply} \quad \vec{F}'(t) = \vec{F}(t) \tag{3}$$

(Careful: a prime does *not* denote a derivative with respect to t!) Now, let W and W' be the works done on m from A to B according to O and O', respectively. We have:

$$W = \int_{A}^{B} \vec{F}(\vec{r}) \cdot d\vec{r} = \int_{A}^{B} \vec{F}\left(\vec{r}(t)\right) \cdot \frac{d\vec{r}}{dt} dt = \int_{A}^{B} \vec{F}(t) \cdot \vec{v}(t) dt$$

and, similarly,

$$W' = \int_{A}^{B} \vec{F}'(\vec{r}') \cdot d\vec{r}' = \int_{A}^{B} \vec{F}'(t) \cdot \vec{v}'(t) dt .$$

Taking (1) and (3) into account, we have:

$$W' = \int_A^B \vec{F}(t) \cdot \vec{v}(t) dt - \int_A^B \vec{F}(t) \cdot \vec{V} dt = W - \vec{V} \cdot \int_A^B \vec{F}(t) dt.$$

By using Newton's 2<sup>nd</sup> law, we have:

$$W' = W - m\vec{V} \cdot \int_{A}^{B} \frac{d\vec{v}}{dt} dt = W - m\vec{V} \cdot \int_{A}^{B} d\vec{v} \implies$$
$$W' = W - m\vec{V} \cdot \left(\vec{v}_{B} - \vec{v}_{A}\right) \tag{4}$$

On the other hand, the change in kinetic energy from A to B is, according to O,

$$\Delta E_{k} = \frac{1}{2}mv_{B}^{2} - \frac{1}{2}mv_{A}^{2}$$

while according to O' and in view of (1),

$$\Delta E_{k}' = \frac{1}{2}m\left(v_{B}'\right)^{2} - \frac{1}{2}m\left(v_{A}'\right)^{2} \equiv \frac{1}{2}m\left(|\vec{v}_{B}'|^{2} - |\vec{v}_{A}'|^{2}\right) = \frac{1}{2}m\left(|\vec{v}_{B} - \vec{V}|^{2} - |\vec{v}_{A} - \vec{V}|^{2}\right).$$

By using the identity

$$|\vec{v} - \vec{V}|^2 = (\vec{v} - \vec{V}) \cdot (\vec{v} - \vec{V}) = v^2 + V^2 - 2\vec{v} \cdot \vec{V}$$

at *A* and *B*, we find:

$$\Delta E_{k}^{\prime} = \frac{1}{2} m \left( v_{B}^{2} - v_{A}^{2} - 2 \vec{v}_{B} \cdot \vec{V} + 2 \vec{v}_{A} \cdot \vec{V} \right) \Rightarrow$$
$$\Delta E_{k}^{\prime} = \Delta E_{k} - m \vec{V} \cdot \left( \vec{v}_{B} - \vec{v}_{A} \right) \tag{5}$$

Subtracting (5) from (4), we have:  $W' - \Delta E_k' = W - \Delta E_k$ . So, *if*  $W - \Delta E_k = 0 \Leftrightarrow W = \Delta E_k$  (i.e., if the work-energy theorem is valid in the *O*-frame) then  $W' = \Delta E_k'$  (the theorem is valid in the *O*'-frame also). In other words, the work-energy theorem is Galilean invariant.

*Exercise:* Demonstrate in a similar way the Galilean invariance of the angular momentum – torque relation

$$\frac{d\vec{L}}{dt} = \vec{r} \times \vec{F} = \vec{T}$$

where  $\vec{L} = m\vec{r} \times \vec{v}$  is the angular momentum of the particle *m* relative to *O*, and where  $\vec{F}$  is the total force on *m* (see Sec. 3.7 of [1]).

[*Hint:* Assume that  $\vec{r}' = \vec{r} - \vec{Vt}$  (this means that the origins *O* and *O'* of the two inertial frames coincide at t=0; as before,  $\vec{V}$  is the constant velocity of *O'* relative to *O*). Evaluate  $\vec{L}' = m\vec{r}' \times \vec{v}'$  and, by using Newton's 2<sup>nd</sup> law, show that

$$\frac{d\vec{L}'}{dt} = \frac{d\vec{L}}{dt} - t\vec{V}\times\vec{F}$$
(6)

Also, show that  $\vec{T}' = \vec{r}' \times \vec{F}'$  is equal to

$$\vec{T}' = \vec{T} - t\vec{V} \times \vec{F} \tag{7}$$

Finally, subtract (7) from (6).]

## Reference

[1] C. J. Papachristou, *Introduction to Mechanics of Particles and Systems* (Springer, 2020), <u>http://metapublishing.org/index.php/MP/catalog/book/68</u>.